

From eigenvector nonlinearities to eigenvalue nonlinearities

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Joint work with Elias Jarlebring (KTH)

Outline for this talk

1. Introduction
2. A motivating application
3. Problem statement & method
4. Numerical example
5. Conclusion and outlook

Introduction

We are concerned with **two types of nonlinear eigenvalue problems**, that have both received significant attention in the NLA community.

Problem 1: NEP_v (our main problem today)

Find eigenpair $(\lambda, v) \in \mathbb{R} \times \mathbb{R}^n$ such that

$$A(v)v = \lambda v, \quad \|v\| = 1,$$

where $A(v) \in \mathbb{R}^{n \times n}$ is symmetric and maps vectors to matrices.

Problem 2: NEP

Find eigenpair $(\lambda, v) \in \mathbb{R} \times \mathbb{R}^n$ such that

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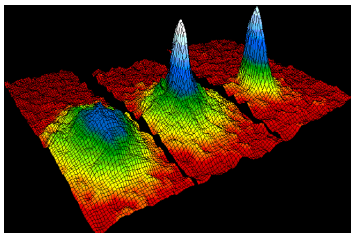
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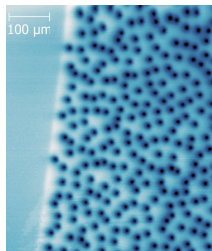
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A motivating application: the Gross-Pitaevskii eq.



Left: velocity distribution in condensate. Source: Nobel prize report '01.



Right: quantized vortices in superconductor. Source: Wells et. al. '15.

- Cooling a gas of bosons to ultra-low temperatures results in an exotic state of matter: a **Bose-Einstein condensate**
- Theoretically predicted in 1925 by Bose and Einstein
- Verified experimentally in 1995 → **Nobel prize to Cornell, Ketterle, and Wieman!**
- Modeled by the **Gross-Pitaevskii** equation (GPE)
- Discretization yields **NEPv** with cubic terms

Stationary GPE, continuous setting

Find $u(x)$, $x \in \mathbb{R}^d$, $d = 2, 3$, and $\lambda \in \mathbb{R}$ such that

$$\underbrace{-\Delta u(x)}_{\text{Kinetic energy}} + \underbrace{V_{tr}(x)u(x)}_{\text{Potential energy}} + \underbrace{\kappa|u(x)|^2 u(x)}_{\text{Particle interactions}} = \lambda u(x), \quad \|u\| = 1.$$

Stationary GPE, discrete setting

Find eigenpair $(\lambda, v) \in \mathbb{R} \times \mathbb{R}^n$ such that

$$\left(-L_n + D + \kappa \left[(e_1^T v)^2 e_1 e_1^T + \cdots + (e_n^T v)^2 e_n e_n^T \right] \right) v = \lambda v, \quad \|v\| = 1.$$

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Finite differences



See, e.g., [Henning, Målqvist,
SIAM J. Numer. Anal. '17], and refs.
for more general discretization techniques

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- Symmetric **NEP** v
- **Ground state** typically the smallest eigenvalue, minimizer of the energy in the system
- Often: interested in a few of the smallest eigenvalues
- Challenge: methods for GPE can find the ground state, but no natural way to find several modes

Detour: methods for NEPs

Recall our second problem for today:

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- A wide variety of efficient methods
 - ▶ Newton methods: Quasi-Newton, Block-Newton, Broyden's method,...
 - ▶ Krylov methods: Rational Krylov, Nonlinear Arnoldi, Infinite Arnoldi,...
 - ▶ Jacobi-Davidson methods
 - ▶ Contour integral methods: Beyn's method,...
 - ▶ Linearization, specialized structures,...

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 - ▶ Linearization, specialized structures,...
- Many methods can find several eigenvalues in a natural way

Our approach (simplified case)

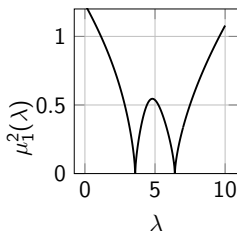
GPE-type **NEP_v**

Via small poly. sys.

Algebraic **NEP**

$$(A_0 + (a_1^T v)^2 a_1 a_1^T) v = \lambda v$$

$$(A_0 + \mu_1^2(\lambda) a_1 a_1^T) v = \lambda v$$



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Then $\mu_1^2(\lambda)$ is given explicitly by the function

$$\mu_1^2(\lambda) = \left(\frac{(\lambda^2 - 10\lambda + 23)^2}{13\lambda^2 - 116\lambda + 281} \right)^{2/3},$$

and the **NEP** $(A_0 - \lambda I + \mu_1^2(\lambda)a_1a_1^T) v = 0$ can be solved with any **NEP**-solver.

Sketch of transformation

GPE-type **NEPv** (single term)

Find eigenpair $(\lambda, v) \in \mathbb{R} \times \mathbb{R}^n$ such that

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$$(A_0 - \lambda I)v + \mu_1^3 a_1 = 0$$

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- Use the normalization $1 = \|v\|^2 = |\mu_1^3| \|(\lambda I - A_0)^{-1} a_1\|^2$
- Finally (use 2-norm and symmetry of A_0):

$$\mu_1^2 = \mu_1^2(\lambda) = \left[\frac{1}{a_1^T (\lambda I - A_0)^{-2} a_1} \right]^{2/3}$$

The general case

GPE-type NEP_v

Find eigenpair $(\lambda, v) \in \mathbb{R} \times \mathbb{R}^n$, $m \leq n$, such that

$$\left(A_0 - \lambda I + (a_1^T v)^2 a_1 a_1^T + \cdots + (a_m^T v)^2 a_m a_m^T \right) v = 0, \quad \|v\|^2 = 1.$$

Equivalent NEP

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- The functions $\mu_1(\lambda), \dots, \mu_m(\lambda)$ are defined implicitly via a **small polynomial system** of $m + 1$ equations in $m + 1$ variables.
- It is derived in a fashion similar to the above example. \rightarrow They exist generically under the assumptions of the implicit function theorem.

Defining $\mu_1(\lambda), \dots, \mu_m(\lambda)$

Equivalent NEP

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Polynomial system

The vector $\mu = [\mu_1, \dots, \mu_m]^T$ satisfies the relations

$$(\mu^3)^T G(\lambda) \mu^3 - 1 = 0,$$

$$P(H(\lambda) \mu^3 - \mu) = 0,$$

with $G(\lambda) = A_m^T (\lambda I - A_0)^{-2} A_m$, $H(\lambda) = A_m^T (\lambda I - A_0)^{-1} A_m$.

- m equations in $m + 1$ variables $(\lambda, \mu_1, \dots, \mu_m) \leftarrow$ **gives implicit functions**

- By construction, **NEP_v**-solutions are **NEP**-solutions. The converse also holds:

Theorem (Thm. 1, Jarlebring, L., 2025)

The polynomial system generically defines functions $\mu(\lambda) = [\mu_1(\lambda), \dots, \mu_m(\lambda)]^T$ such that for any (λ_, v_*) , the following two statements are equivalent.*

- *The pair (λ_*, v_*) is a solution to the **NEP_v**.*
- *The pair (λ_*, v_*) is a solution to the **NEP** with the functions defined by μ and $\|v_*\| = 1$.*

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 - ▶ *The pair (λ_*, v_*) is a solution to the **NEP** with the functions defined by μ and $\|v_*\| = 1$.*
- The polynomial system must be solved for every evaluation of **NEP**
 - **We need robust solver for polynomial-system**
 - **Reformulate into multiparameter-eigenvalue problem (**MEP**)**

Solving the polynomial system (sketch)

$$\begin{aligned}(\mu^3)^T G(\lambda) \mu^3 - 1 &= 0 \\ P(H(\lambda) \mu^3 - \mu) &= 0\end{aligned}$$

$$w := \mu^3$$

$$\begin{aligned}w^T G(\lambda) w - 1 &= 0 \\ P((H(\lambda) w)^3 - w) &= 0\end{aligned}$$

"Black box" software
(HomotopyContinuation.jl,...)

Reformulation as **MEP**
(Companion linearization)

Solutions
to poly. syst.
→ **NEP**-eval.

MEP-techniques

$$\begin{aligned}(A_{10} + w_1 A_{11} + \cdots + w_m A_{1m})x &= 0 \\ &\vdots \\ (A_{m0} + w_1 A_{m1} + \cdots + w_m A_{mm})x &= 0\end{aligned}$$

Operator determinants, GEP
(Gives all sols of poly-sys)

Numerical example (1/4)

We consider a **NEP_v** with $m = 5$ nonlinear terms. The problem is derived from an eigenvalue problem in \mathbb{R}^2 .

GPE-type eigenproblem (continuous setting)

Find $u(x, y)$ and $\lambda \in \mathbb{R}$ such that

$$-\Delta u(x, y) + p(x, y)u(x, y) + \sum_{i=1}^m \phi_i^3(u)\psi_i(x, y) = \lambda u(x, y),$$

with $\|u\|_{L^2} = 1$, and where the functionals $\phi_i(u)$ are defined by

$$\phi_i(u) = \int_{\Omega} \psi_i(x, y)u(x, y)d\Omega.$$

- $p(x, y)$ = potential function, harmonic oscillator + optical lattice
- $\psi_i(x, y)$ = Gaussians localized in different points (\times in figs)

Numerical example (2/4)

- Discretize with FDs + trapezoidal rule for integrals
- We get the discrete **NEP** \mathbf{v} :

GPE-type eigenproblem (discrete setting)

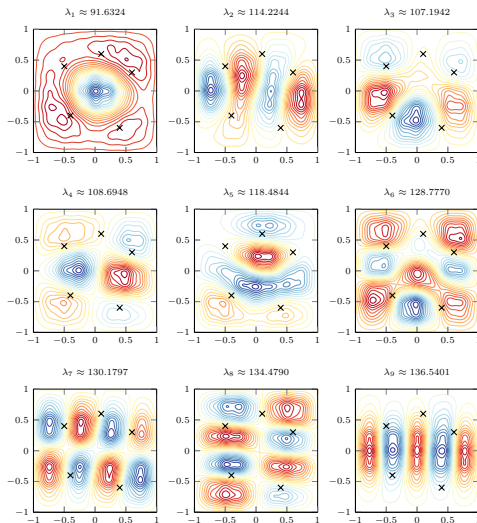
Find eigenpair $(\lambda, \mathbf{v}) \in \mathbb{R} \times \mathbb{R}^{N^2}$ such that

$$\left(-L_{N^2} + D + \sum_{i=1}^m (a_i^T \mathbf{v})^2 a_i a_i^T \right) \mathbf{v} = \lambda \mathbf{v}$$

- We solve the **NEP** \mathbf{v} by solving the equivalent **NEP**.
- **NEP** solved with Augmented Newton method + deflation of already computed eigs (see, e.g., [Effenberger, '13])

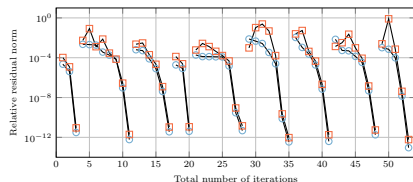
Numerical example (3/4)

Computed eigenmodes (65536×65536 problem):

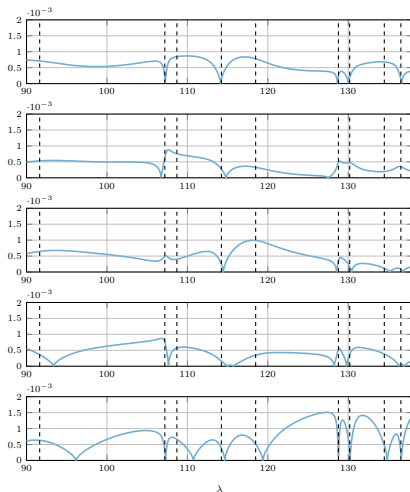


Numerical example (4/4)

Convergence history and μ -functions (65536 \times 65536 problem):



(a) Convergence history



(b) μ -functions

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Continued work

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Continued work

- To actually solve the GPE, we need n nonlinear terms. Our approach handles $m \ll n$ comfortably, but $m \approx n$ becomes more difficult.
- Can the GPE be well approximated with only a small number of terms?
- "Easy" generalization: replace squares with more general functions

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Thank you for your attention!

Preprint: <https://arxiv.org/abs/2506.16182>